

Design of fishing exclusion zones

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Problem statement

The goal is to:

- Ensure the survival of endangered fish by achieving balance between fishing, birth, and movement rates.
- Compare the effectiveness of different geometries of exclusion zones.
- Improve on the current mathematical model by modifying the source term.
- Finding parameter values using known data.

Single species model

Reaction-diffusion equation:

$$\theta_t = -\nabla \cdot \underline{q} + S(\theta, \underline{x}). \quad (1)$$

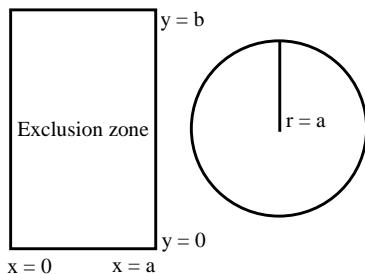
Using Fick's law we get

$$\theta_t = \nabla \cdot [D(\theta)\nabla\theta] + f(\underline{x})R(\theta). \quad (2)$$

Possible modifications:

- Consider a time-dependent domain. Using the Reynolds transport theorem we can show that equation (1) still holds with $\underline{q} = -D(\theta)\nabla\theta + \theta\underline{u}$ where \underline{u} is the velocity of the domain.
- Previous models for circular geometries use $f(r) = 1$ and $R(\theta) = s\theta(1 - \theta/m)$. We will consider a Gaussian distribution.

Comparison of different geometries



We first linearise the governing equation for small θ and small $|\nabla\theta|$ which gives

$$\theta_t = D(0)\nabla^2\theta + s\theta. \quad (3)$$

Comparison of different geometries

Now consider a rectangular domain with length a and width b . For now let $f(x, y) = 1$. Use separation of variables to get a basis of solutions. We find that

$$\theta = A \exp[A_{lm}t] \sin(xl\pi/a) \sin(ym\pi/b), \quad (4)$$

where

$$A_{lm} = -D_0 \left(\frac{m^2\pi^2}{b^2} + \frac{l^2\pi^2}{a^2} \right) + s. \quad (5)$$

For $A_{11} > 0$, the population will increase. This gives a result in terms of the hyperbolic rms length

$$\frac{1}{\sqrt{1/(2b^2) + 1/(2a^2)}} > 2\pi\sqrt{D(0)/s}. \quad (6)$$

Comparison of different geometries

Rearranging allows us to write this expression as a ratio of area to diagonal

$$\frac{ab}{\sqrt{a^2 + b^2}} > \pi \sqrt{2D(0)/s}. \quad (7)$$

For a square we have

$$a > 2\pi \sqrt{D(0)/s} \quad (8)$$

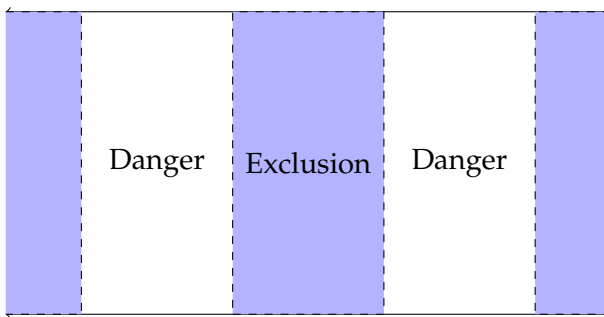
- Reduction of 2-D model to 1-D model gives

$$a > \pi \sqrt{D(0)/s}. \quad (9)$$

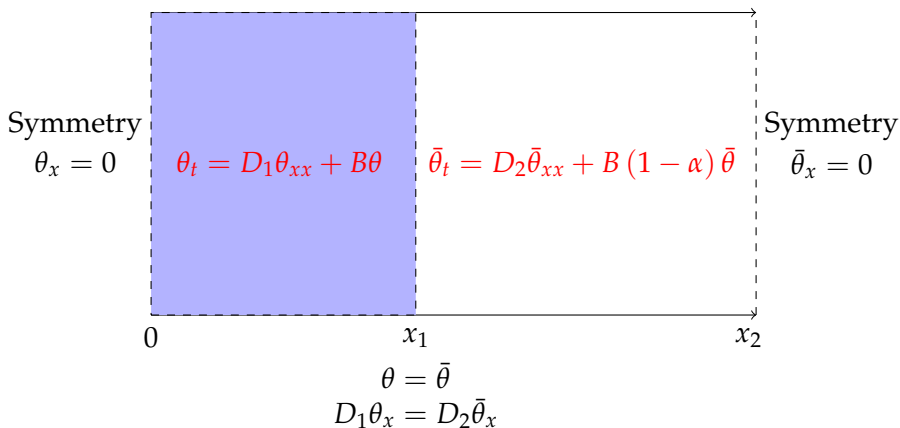
- For a circular geometry

$$a > \lambda_1 \sqrt{D(0)/s}, \quad J_0(\lambda_1) = 0. \quad (10)$$

Infinite series of zones



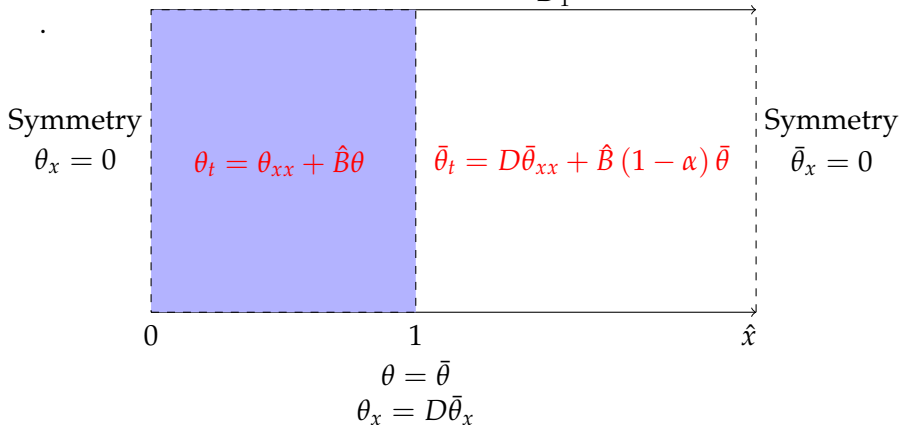
Dimensional model



Dimensionless model

Employ the scaling

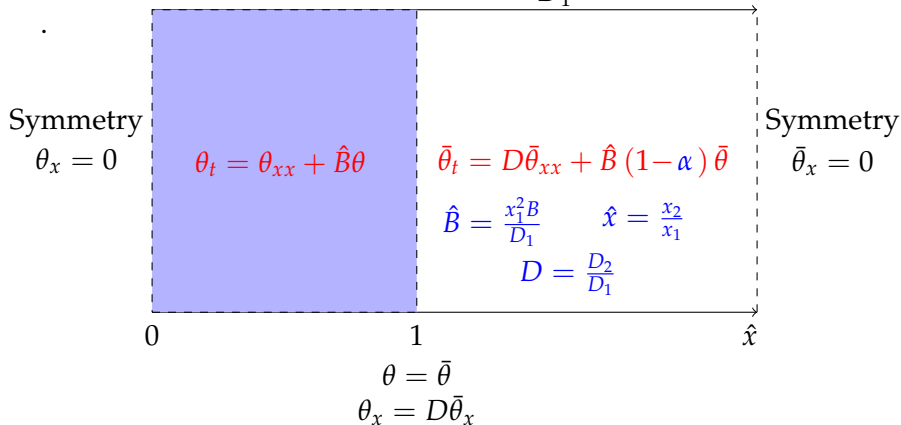
$$x = x_1 x', \quad t = \frac{x_1^2}{D_1} t'$$



Dimensionless model

Employ the scaling

$$x = x_1 x', \quad t = \frac{x_1^2}{D_1} t'$$



Solution in zone I

- Variable separable solution for the population density function $\theta = X(x)T(t)$ furnishes the general solution in I

$$T = T(0) \exp(\lambda^2 t) \quad (11)$$

- Two cases

$$\text{Case 1 : } X(x) = A_1 \cos(\omega_1 x), \quad \hat{B} - \lambda^2 > 0 \quad (12)$$

$$\text{Case 2 : } X(x) = A_1 \cosh(\omega_1 x), \quad \hat{B} - \lambda^2 < 0 \quad (13)$$

where $\omega_1^2 = \text{Abs}[(\hat{B} - \lambda^2)]$.

Solution in zone II

- Variable separable solution for the population density function $\theta = X(x)T(t)$ unearths the general solution in II

$$T = T(0) \exp(\lambda^2 t) \quad (14)$$

- Two cases, but we are really interested in the case where $\alpha > 1$.

$$\text{Case A : } X(x) = A_1 (\cosh(\bar{\lambda}x) - \tanh(\bar{\lambda}x_2) \sinh(\bar{\lambda}x)) \quad (15)$$

where

$$-\bar{\lambda}^2 = \hat{B}[(1 - \alpha) - \lambda^2] \quad (16)$$

Interface conditions

The dimensionless interface conditions at $x = x_2$ are

$$\theta = \bar{\theta}, \quad \theta_x = D\bar{\theta}_x. \quad (17)$$

For Case 1 and Case A this leads to

$$\frac{\sqrt{\hat{B} - \lambda^2} \coth \left[(\hat{x} - 1) \sqrt{\hat{B} - \hat{B}\alpha - \lambda^2} \right] \tan \left[\sqrt{\hat{B} - \lambda^2} \right]}{D\sqrt{\hat{B} - \hat{B}\alpha - \lambda^2}} = 1. \quad (18)$$

For $\lambda = 0$:

$$\frac{\coth \left[(\hat{x} - 1) \sqrt{\hat{B} - \hat{B}\alpha} \right] \tan \left[\sqrt{\hat{B}} \right]}{D\sqrt{1 - \alpha}} = 1. \quad (19)$$

Condition for marginal stability

- The hyper-surface in $(\hat{B}, \alpha, D, \hat{x})$ space defined by

$$\frac{\coth \left[(\hat{x} - 1) \sqrt{\hat{B}(1 - \alpha)} \right] \tan \left[\sqrt{\hat{B}} \right]}{D \sqrt{1 - \alpha}} = 1, \quad (20)$$

separates region of different stability.

- Can use (20) to evaluate conservation strategies.

Conservation strategy

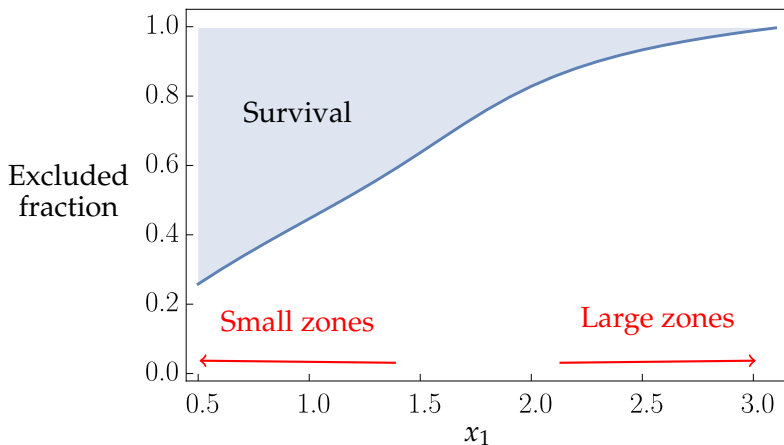


Figure: Fraction of river that must be excluded. Sample parameters:
 $D = 1$, $\alpha = 5$, and $B = 1$

Stability analysis for modified reactive diffusion model

- Environmental heterogeneous factor is a parabolic curve.
- Model

$$\theta_t = D\theta_{xx} + (1 - \epsilon x^2) B\theta \quad (21)$$

- Variable separable solution $\theta = e^{At}Q(x)$, where

$$Q(x) = e^{-\frac{1}{4}x^2} M\left(\frac{1}{2}a + \frac{1}{4}, \frac{1}{2}, \frac{1}{2}x^2\right) \quad (22)$$

and

$$a = \frac{1}{2} \frac{A - B}{D(0)^{\frac{1}{2}}} (B\epsilon)^{-\frac{1}{2}}$$

Linear stability analysis

$$\theta_t = D(0)\theta_{xx} + s\theta f(x),$$

$$\theta = P(t)Q(x),$$

$$A = \frac{P'(t)}{p} = D(0) \frac{Q''(x)}{Q} + s(1 - \epsilon x^2)$$

$$Q'' + \left[\frac{s - A}{D(0)} - \frac{\epsilon s x^2}{D(0)} \right] Q = 0,$$

$$\bar{x} = \frac{x}{\ell}, \ell = \frac{1}{\sqrt{2}} \left[\frac{D(0)}{\epsilon s} \right]^{\frac{1}{4}}.$$

$$Q'' - \left[a + \frac{1}{4}\bar{x}^2 \right] Q = 0,$$

$$a = \frac{1}{2} \left[\frac{D(0)}{\epsilon s} \right]^{\frac{1}{2}} \frac{A - s}{D(0)}.$$

First approximation linear stability analysis

We consider the even solution

$$Q(x) = l^{-2} e^{-\frac{1}{4}\bar{x}^2} M \left(\frac{1}{2}a + \frac{1}{4}, \frac{1}{2}, \frac{1}{2}\bar{x}^2 \right),$$

First zero approximation (Abramowitz Stegun) occurs when

$$\bar{x}^2 = \frac{\pi^2 \left(1 + \frac{1}{4} - \frac{3}{4}\right)^2}{1 - 2a - 1},$$

$$\bar{x}^2 = \frac{\pi^2}{-4a}.$$

Stability cross-over

$$2x_1 > \pi \left[\frac{D(0)}{s} \right]^{\frac{1}{2}},$$

which concurs with findings above. Next correction by the Newton-Raphson method is less than 1% ($f = 1$ at bddy).

Finding parameter values using data

- We have 6000 data points for fish movement.
- Fit the probability density function:

$$P = \alpha(\pi D_1 t)^{-1/2} \exp[-x^2/4D_1 t] + (1 - \alpha)(\pi D_2 t)^{-1/2} \exp[-x^2/4D_2 t]. \quad (23)$$

So we have two sub-populations, namely, home-bodies and travellers which was considered in the previous model.

Statistical confirmation

- Data maintained on Oceanographic Research Institute's Cooperative Fish Tagging Project.
- Need to confirm model with paper by Bruce et al 2016.
- The diffusivity coefficient $D = \frac{x_i^2}{2\pi t_i}$ will be furnished by random walk analysis.

Numerical simulations

- Lie point symmetries of the non-linear equations.
- Perturbation methods.
- Numerical solutions of the full non-linear equations.
- Question the applicability of Fick's law.
- Consider a moving boundary.

Conclusions

- The square is the best geometry!
- A simple 1-D model provides a simple framework for assessing conservation strategies.
- Including the parabolic adjustment gives no further information at the lowest order.

"So long and thanks for all the fish!"